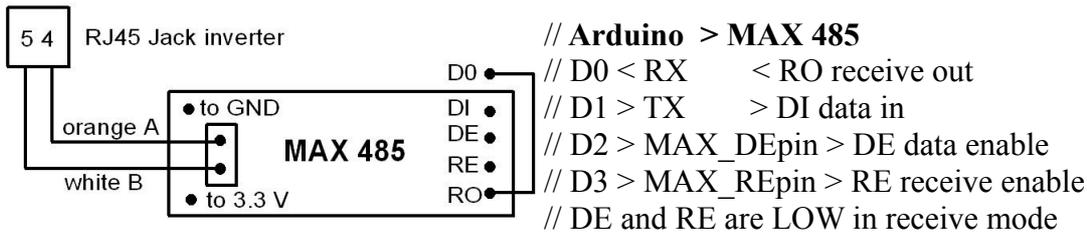


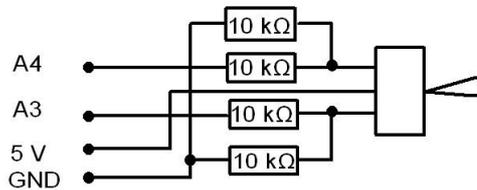
// **_250810A_Solax_ClockStarted_SocketSwitchAndLog**

Inverter connection

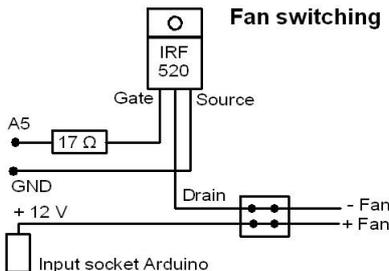


- // **Arduino** > **MAX 485**
- // D0 < RX < RO receive out
- // D1 > TX > DI data in
- // D2 > MAX_DEpin > DE data enable
- // D3 > MAX_REpin > RE receive enable
- // DE and RE are LOW in receive mode
- // RS485 A > orange > RJ45 pin 4 SOLAX Inverter
- // RS485 B > white > RJ45 pin 5 SOLAX inverter
- // 3.3 V > yellow > MAX VCC (Voltage Common Collector)
- // GND > black > MAX GND
- // **Arduino** > **Real Time Clock module DS 1302 CR2032 battery**
- // D5 RTC_CEpIn > white > CE Chip Enable
- // D6 > orange > SCLK Clock signal
- // D7 > brown > I/O data
- // 5V block > yellow > VCC
- // GND block > black > GND
- // **Arduino** > **Voltmeter displaying temperature**
- // D8 Display_VCC > red > VCC meter (on/off time controlled)
- // D9 Displ_value > yellow > Data meter
- // GND block > black > GND meter
- // **Arduino** > **SDCard logger module**
- // D10 SD_CS > brown > CS Chip Select
- // D11 > red > MOSI Master Out Slave In
- // D12 > grey > MISO Master In Slave Out
- // D13 > purple > CLK Clock signal
- // GND > grey > GND
- // 5V > yellow > VCC
- // A2 GREEN_Log > 1kΩ > **green LED** on SD GND pin D
- // D4 BLUE_SD_RC1 > 1kΩ > **blue LED** on SD GND pin
- // **Arduino** > **433MHz TX module** on headerpins A0 and A1
- // A0 RC_TX_VCC > VCC
- // A1 RC_TX_DAT > DAT
- // GND header > blue > GND
- // **Arduino** > **3-way switch**
- // A3 Mode_ONpin > blue > 3-way switch up
- // A4 Mode_OFFpin > brown > switch down
- // 5V > yellow > middle pin
- // GND > black > pulldown resistors

3-way mode switch



Fan switching



- // A5 FanPin > 17Ω > IRF520 Gate
- // GND > IRF520 Source
- // IRF520 Drain > connection block > Fan -
- // +12V input socket > red > connection block > Fan +

```

#include <SPI.h>           // used for SD
#include <SD.h>
#include "DS1302.h"       // real time clock module
#include <SoftwareSerial.h>

#define RC_TX_VCC  A0
#define RC_TX_DAT  A1
#define GREEN_Log  A2
#define Mode_ONpin A3
#define Mode_OFFpin A4
#define FanPin     A5

#define MAX_SSerialRX 0
#define MAX_SSerialTX 1
#define MAX_DEpin     2
#define MAX_REpin     3
#define BLUE_SD_RC1   4
#define RTC_CEpins    5
#define RTC_IOpins    6
#define RTC_SLKpin    7
#define Display_VCC   8
#define Display_value 9
#define SD_CS         10

SoftwareSerial RS485Serial(MAX_SSerialRX, MAX_SSerialTX);
DS1302 rtc(RTC_CEpins, RTC_IOpins, RTC_SLKpin);
Time t = rtc.time();
File logfile;

// Declarations for inverter data retrieving
byte AddressInput[] = {0xAA,0x55,0x00,0x00, 0x00,0x00, 0x10, 0x01, 0x0F,
//           Header, AccesPoint, Solax X1 ,Contr, Func, Length
0x31,0x32,0x33,0x34,0x35,0x36,0x37,0x37,0x36,0x35,0x34,0x33,0x32,0x31,
0x0A,0x04,0x01};
// Serialnumber data 0 ----->13 ,address, checksum
byte RequestData[]={0xAA,0x55, 0x00,0x00, 0x00,0x0A , 0x11, 0x02, 0x00, 0x01,0x1C};
//           Header , Source , SOLAX ,Control,Func,Length, Check 2b
byte DataInput[63];
byte InByte = 0;
bool dataValid = false;

// Inverter/Sockets on-off settings and declarations
byte hour_SolaxStart = 9; // recording and socketswitching
byte hour_SolaxEnd = 21; // end daytime/ RCsocket switching
int power_RCA_Off = 1450; // boiler 1385 (power in watts)
int power_RCA_On = 1550; // measured 250614
int power_RCBPlus_Off = 1950; // when RCA is on
int power_RCBPlus_On = 2050; // when RCA is on
int power_RCB_Off = 650; // when RCA is off
int power_RCB_On = 750; // when RCA is off
int power_RCC_Off = 1150; // when RCA is off & RCB on
int power_RCC_On = 1250; // when RCA is off & RCB on

```

```

int power_Solax = 0;    // data from inverter
int  voltvalue = 0;
byte temp_Fan_On = 35; // °C
byte temp_Fan_Off = 33;
byte temp_Solax = 0;
int switchdelay = 6000; // millisecs delay before switching
int loopdelay = 9000; // 9 seconds
byte MenuChoice = 2; // switch condition
bool daytime = false; // monitorring inverter off
bool socketA_allowedOn = false; // set by powervalue inverter or
bool socketB_allowedOn = false; // 3-way menuchoice switch
bool socketC_allowedOn = false;
bool socketA_switchedOn = false; // runtime situation
bool socketB_switchedOn = false;
bool socketC_switchedOn = false;

```

// RC code setting for the used RC switches

// delay times (pinData HIGH or LOW situations) in μ seconds:

```

#define Bit24HighUp 998 //44 samplepoints
#define Bit24HighDown 476 //21 samplepoints
#define Bit24LowUp 295 //13 samplepoints
#define Bit24LowDown 1179 //52 samplepoints

```

```

#define Bit32HighUp 1429 //66 samplepoints
#define Bit32HighDown 590 //26 samplepoints
#define Bit32LowUp 408 //18 samplepoints
#define Bit32LowDown 1610 //71 samplepoints

```

```

#define StartDelay24LowUp 400
#define StartDelay24LowDown 2250
#define StartDelay32LowUp 408
#define StartDelay32LowDown 7188

```

// commands for the 3 sockets; 24 bit pattern is send 6x, 32 bit pattern 4x

```

bool S24[6][24] = { {0,0,1,1,0,0,0,0,1,0,1,1,1,0,1,0,0,0,1,1,0,1,0,1}, // A_ON
                   {0,0,1,1,0,1,1,1,0,0,0,0,1,1,0,1,0,1,0,0,0,1,0,1}, // A_OFF
                   {0,0,1,1,1,0,1,1,1,1,0,0,0,0,1,1,0,1,1,0,1,1,0,0}, // B_ON
                   {0,0,1,1,1,1,0,0,1,1,1,0,1,1,0,0,1,1,1,1,0,0}, // B_OFF
                   {0,0,1,1,0,1,1,0,1,1,1,0,0,0,0,1,1,0,1,1,1,1,0}, // C_ON
                   {0,0,1,1,0,1,0,1,0,1,1,0,1,0,0,0,0,0,0,1,1,1,0} }; // C_OFF

```

```

bool S32[6][32] =
  { {0,0,1,1,1,0,1,0,1,1,1,1,0,1,1,1,1,1,1,1,0,0,1,1,0,1,0,1,0,1}, // A_ON
    {1,0,1,1,1,1,0,0,1,1,1,0,1,1,1,0,0,1,1,0,1,1,1,1,0,0,1,0,1,0,1}, // A_OFF
    {1,1,1,1,0,0,0,1,0,1,0,1,1,1,1,1,1,1,1,1,0,1,0,1,1,0,0,1,0,0,1,1}, // B_ON
    {1,0,0,0,1,0,1,1,1,0,0,0,1,1,1,0,1,0,0,1,1,0,0,0,1,0,0,1,0,0,1,1}, // B_OFF
    {1,1,1,1,1,1,1,1,1,0,1,1,0,0,1,1,0,1,0,1,0,0,1,1,0,1,1,0,1,1,0,1}, // C_ON
    {1,1,0,1,0,0,1,1,0,0,1,0,0,0,0,1,1,0,0,0,0,0,0,1,1,0,0,1,1,0,1,1} }; // C_OFF

```

// Function to send the TX signal dependend on socket and command

void switchRC(byte commandNumber)

```

{
  byte bitNumber;

```

```

byte bitPattern;
for (bitPattern = 0; bitPattern < 6; bitPattern++) // 24 bit part 6 times
{
  // start with extra LOW part
  digitalWrite(RC_TX_DAT, HIGH);
  delayMicroseconds(StartDelay24LowUp);
  digitalWrite (RC_TX_DAT, LOW);
  delayMicroseconds(StartDelay24LowDown);
  for (bitNumber = 0; bitNumber < 24; bitNumber++)
  {
    if (S24[commandNumber][bitNumber] == HIGH)
    {
      digitalWrite (RC_TX_DAT, HIGH);
      delayMicroseconds(Bit24HighUp);
      digitalWrite (RC_TX_DAT, LOW);
      delayMicroseconds(Bit24HighDown);
    }
    else
    {
      digitalWrite (RC_TX_DAT, HIGH);
      delayMicroseconds(Bit24LowUp);
      digitalWrite (RC_TX_DAT, LOW);
      delayMicroseconds(Bit24LowDown);
    }
  }
}
for (bitPattern = 0; bitPattern < 4; bitPattern++) // 32bits part 4 times
{
  //start with an extra long LOW
  digitalWrite (RC_TX_DAT, HIGH);
  delayMicroseconds(StartDelay32LowUp);
  digitalWrite (RC_TX_DAT, LOW);
  delayMicroseconds(StartDelay32LowDown);
  for (bitNumber = 0; bitNumber < 32; bitNumber++)
  {
    if (S32[commandNumber][bitNumber] == HIGH)
    {
      digitalWrite (RC_TX_DAT, HIGH);
      delayMicroseconds(Bit32HighUp);
      digitalWrite (RC_TX_DAT, LOW);
      delayMicroseconds(Bit32HighDown);
    }
    else
    {
      digitalWrite (RC_TX_DAT, HIGH);
      delayMicroseconds(Bit32LowUp);
      digitalWrite (RC_TX_DAT, LOW);
      delayMicroseconds(Bit32LowDown);
    }
  }
}
}
}
}

```

```

void SetMenu()    // check the 3 way switch
{
  if(analogRead(Mode_ONpin) > 500) // (read values 0-1024)
    MenuChoice = 1; //Boilersocket always on (UP)
  if(analogRead(Mode_OFFpin) > 500)
    MenuChoice = 3; //Boilersocket always off (DOWN)
  if((analogRead(Mode_ONpin) < 500) && (analogRead(Mode_OFFpin) < 500))
    MenuChoice = 2; // Boilersocket power_Solax regulated
}

```

```

// Function to assign an address to the Solax inverter
void AssignAddress()
{
  digitalWrite(MAX_REpin, HIGH); // MAX 485 in send mode
  digitalWrite(MAX_DEpin, HIGH);
  RS485Serial.write(AddressInput,sizeof(AddressInput));
  delay(10000);
}

```

```

void setSwitchConditions(int mode)
{
  // set conditions
  if (mode == 1) // RCA(Boiler)always on
  {
    socketA_allowedOn = true;
    socketB_allowedOn = false;
    socketC_allowedOn = false;
    if(power_Solax >= power_RCBPlus_On)
      socketB_allowedOn = true;
    if((power_Solax < power_RCBPlus_Off) && (socketB_allowedOn == true))
    {
      delay(switchdelay); // delay and measure again
      GetSolaxData();
      if(power_Solax < power_RCBPlus_Off)
        socketB_allowedOn = false;
    }
  }
  if (mode == 2) // all sockets power_Solax regulated
  {
    if(power_Solax >= power_RCA_On)
    {
      socketA_allowedOn = true;
      socketB_allowedOn = false;
      socketC_allowedOn = false;
    }
    if(power_Solax >= power_RCBPlus_On)
    {
      socketA_allowedOn = true;
      socketB_allowedOn = true;
      socketC_allowedOn = false;
    }
    if((power_Solax < power_RCBPlus_Off) && (socketB_allowedOn == true))

```

```

{
  delay(switchdelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCBPlus_Off)
    socketB_allowedOn = false;
}
if((power_Solax >= power_RCB_On) && (power_Solax <= power_RCA_Off))
{
  socketA_allowedOn = false;
  socketB_allowedOn = true;
  socketC_allowedOn = false;
}
if((power_Solax >= power_RCC_On) && (power_Solax <= power_RCA_Off))
{
  socketA_allowedOn = false;
  socketB_allowedOn = true;
  socketC_allowedOn = true;
}
if((power_Solax < power_RCA_Off) && (socketA_allowedOn == true))
{
  delay(switchdelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCA_Off)
    socketA_allowedOn = false;
}
if((power_Solax < power_RCC_Off) && (socketC_allowedOn == true))
{
  delay(switchdelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCC_Off)
    socketC_allowedOn = false;
}
if((power_Solax < power_RCB_Off) && (socketB_allowedOn == true))
{
  delay(switchdelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCB_Off)
    socketB_allowedOn = false;
}
}
}
if(mode == 3) // RCA (boiler) off switch B and C
{
  socketA_allowedOn = false;
  if(power_Solax >= power_RCB_On)
    socketB_allowedOn = true;
  if((power_Solax < power_RCB_Off) && (socketB_allowedOn == true))
  {
    delay(switchdelay); // delay and measure again
    GetSolaxData();
    if(power_Solax < power_RCB_Off)
      socketB_allowedOn = false;
  }
}
}

```

```

if(power_Solax >= power_RCC_On)
  socketC_allowedOn = true;
if((power_Solax < power_RCC_Off) && (socketC_allowedOn == true))
{
  delay(switchdelay); // delay and measure again
  GetSolaxData();
  if(power_Solax < power_RCC_Off)
    socketC_allowedOn = false;
}
}
}
}
void switchRC_Sockets()
{
  if((socketA_allowedOn == true) && (socketA_switchedOn == false))
  {
    switchRC(0); //Switch Socket A ON
    digitalWrite(BLUE_SD_RC1, HIGH);
    switchRC(5); //Switch Socket C OFF because it switches ON with A
    socketA_switchedOn = true;
  }
  if((socketB_allowedOn == true) && (socketB_switchedOn == false))
  {
    switchRC(2); //Switch Socket B ON
    socketB_switchedOn = true;
  }
  if((socketC_allowedOn == true) && (socketC_switchedOn == false))
  {
    switchRC(4); //Switch Socket C ON
    socketC_switchedOn = true;
  }
  if((socketA_allowedOn == false) && (socketA_switchedOn == true))
  {
    switchRC(1); //Switch Socket A off
    digitalWrite(BLUE_SD_RC1, LOW);
    socketA_switchedOn = false;
  }
  if((socketC_allowedOn == false) && (socketC_switchedOn == true))
  {
    switchRC(5); //Switch Socket C Off
    socketC_switchedOn = false;
  }
  if((socketB_allowedOn == false) && (socketB_switchedOn == true))
  {
    switchRC(3); //Switch Socket B Off
    socketB_switchedOn = false;
  }
}
}
}

```

void GetSolaxData()

```
{
  byte index = 0;
  power_Solax = 0;
  dataValid = false;
  digitalWrite(MAX_REpin, HIGH); // MAX 485 in send mode
  digitalWrite(MAX_DEpin, HIGH);
  delay(200);
  RS485Serial.write(RequestData,sizeof(RequestData));
  digitalWrite(MAX_REpin, LOW); // MAX 485 in receive mode
  digitalWrite(MAX_DEpin, LOW);
  delay(500);
  while(RS485Serial.available())
  {
    InByte = (byte)RS485Serial.read();
    DataInput[index] = InByte;
    index++;
  } // update the data values of interest and voltmeter(temp)
  power_Solax = DataInput[28] + 256 * DataInput[27];
  if((power_Solax > 0) && (power_Solax < 4000))
  {
    temp_Solax = DataInput[10];
    voltvalue = temp_Solax * 5.1;
    if (voltvalue >= 255)
      voltvalue -= 255;
    analogWrite(Display_value,voltvalue);
    dataValid = true;
    digitalWrite(Display_VCC,HIGH); // Display on
  }
  if(dataValid == false)
    digitalWrite(Display_VCC,LOW); // Display off
}
void(* resetFunc) (void) = 0; // used for daily reset
```

void LogData()

```
{
  // log time, watts, yield_day, yield total and temp
  char timestring[5];
  sprintf(timestring, "%02d:%02d", t.hr,t.min);
  logfile.print(timestring + String(" "));
  sprintf(timestring, "");
  sprintf(timestring, "%04d", power_Solax);
  logfile.print(timestring + String(" "));
  // convert yieldvalue parts first to kWh to stay within 4 bytes data-limit of float
  float yieldtoday = 25.6 * DataInput[11] + DataInput[12]/10.0;
  logfile.print(yieldtoday + String(" "));
  yieldtoday = DataInput[34]/10.0 + 25.6 * DataInput[33] + 6553.6 * DataInput[32] +
    1677721.6 * DataInput[31]; // total yield of the inverter
  logfile.print(yieldtoday + String(" "));
  logfile.println(String(temp_Solax));
  logfile.flush();
}
```

```

void setup()
{
  RS485Serial.begin(9600); // set data rate
  dataValid = false;
  daytime = false;
  pinMode(RC_TX_VCC, OUTPUT); // A0
  pinMode(RC_TX_DAT, OUTPUT); // A1
  pinMode(GREEN_Log, OUTPUT); // A2
  pinMode(Mode_ONpin, INPUT); // A3
  pinMode(Mode_OFFpin, INPUT); // A4
  pinMode(FanPin, OUTPUT); // A5
  pinMode(MAX_SSerialRX, INPUT); // DO RO ReceiveOut
  pinMode(MAX_SSerialTX, OUTPUT); // D1 DI DataIn
  pinMode(MAX_DEpin, OUTPUT); // D2 DE Data Enable
  pinMode(MAX_REpin, OUTPUT); // D3 RE Receive Enable
  pinMode(BLUE_SD_RC1, OUTPUT); // D4
  pinMode(Display_VCC, OUTPUT); // D8
  pinMode(Display_value, OUTPUT); // D9
  pinMode(SD_CS, OUTPUT); // D10 Chip select
  digitalWrite(MAX_REpin, LOW); // receive mode
  digitalWrite(MAX_DEpin, LOW);
  digitalWrite(FanPin, LOW); // Fan off
  delay(2000);
  digitalWrite(BLUE_SD_RC1, LOW); // LED off
  digitalWrite(GREEN_Log, LOW); // LED off
  digitalWrite(Display_VCC, LOW); // Display off
  digitalWrite(RC_TX_VCC, HIGH); // TX RCSockets on
  switchRC(1);
  switchRC(3);
  switchRC(5);

  Time t = rtc.time();
  delay(500);
  char logname[12];
  sprintf(logname,"Solx%02d%02d.TXT", t.yr-2000, t.mon);
  if (!SD.begin(SD_CS)) // Initializing SD card..
  {
    digitalWrite(BLUE_SD_RC1, HIGH); // Card failed/ not present
    return;
  }
  logfile = SD.open(logname, FILE_WRITE);
  if(!logfile)
    digitalWrite(BLUE_SD_RC1, HIGH); // Couldn't create file
  logfile.println();
  logfile.println(logname);
  logfile.println();
  logfile.print("Time Watt kWh/d" + String(t.date));
  logfile.println(" kWh °C");
  logfile.flush();
  delay(2000);
  AssignAddress();
}

```

```

void loop()
{
  t = rtc.time();
  delay(200);
  // * * * * 10 minutes before start * * * *
  if((t.hr == ( hour_SolaxStart - 1 )) && (t.min == 50))
  {
    if ((t.sec >= 0) && (t.sec < 10))
    {
      delay(60000); // be sure to startup for the day only once
      resetFunc();
    }
  }
  t = rtc.time();
  delay(200);
  // * * * * daytime (start- to endtime) * * * *
  if ((t.hr >= hour_SolaxStart) && (t.hr < hour_SolaxEnd))
  {
    daytime = true;
    GetSolaxData();
    if(dataValid == true)
    {
      digitalWrite(Display_VCC,HIGH); // Display on
      if(DataInput[10] >= temp_Fan_On)
        digitalWrite(FanPin, HIGH); // Fan on
      if(DataInput[10] < temp_Fan_Off)
        digitalWrite(FanPin, LOW); // Fan off
      SetMenu(); // check the 3-way menu switch
      delay(200);
      setSwitchConditions(MenuChoice);
      switchRC_Sockets(); //switch the sockets if necessary
      t = rtc.time();
      if((t.sec >= 0) && (t.sec < 10)) // once a minute
      {
        GetSolaxData(); // refresh data and temp readout
        if(dataValid == true)
        { // log every 10 minutes
          if ((t.min == 0) || (t.min == 10) ||
              (t.min == 20) || (t.min == 30) ||
              (t.min == 40) || (t.min == 50) )
          {
            // Show green LED to allow visual check of RTC timeshift
            digitalWrite(GREEN_Log, HIGH); // Green LED on
            LogData(); // write data on SD
            delay(5000);
            digitalWrite(GREEN_Log, LOW); // Green LED off
          }
          delay(9000); // to be sure to log once every 10 minutes
        }
      }
    }
  }
}

```

```

// * * * * "night" time * * * *
if (t.hr >= hour_SolaxEnd)
{
  if (daytime == true)
  {
    dataValid = false;
    digitalWrite(FanPin, LOW);
    digitalWrite(GREEN_Log, LOW);
    digitalWrite(Display_VCC, LOW);
    digitalWrite(RC_TX_VCC, LOW);
    daytime = false;
  }
  delay(loopdelay); // extra delay at night
}
delay(loopdelay);
}
/*

```

Sketch uses 21372 bytes (66%) of program storage space.

Global variables use 1522 bytes (74%) of dynamic memory, leaving 527 bytes for local variables

Sample Datalogging for day 20 of month 8:

Solx2508.TXT

Time	Watt	kWh/d20	kWh	°C
09:00	0299	0.20	10116.00	31
09:10	0237	0.20	10116.00	31
09:20	0222	0.30	10116.10	32
09:30	0356	0.30	10116.10	32
09:40	0469	0.40	10116.20	33
09:50	0603	0.50	10116.30	34
10:00	0507	0.50	10116.30	32
10:10	0406	0.60	10116.40	34
10:20	0615	0.70	10116.50	34
10:30	0737	0.80	10116.60	33
10:40	0935	0.90	10116.70	34
10:50	0522	1.10	10116.90	33
11:00	0600	1.20	10117.00	34
11:10	1203	1.30	10117.10	33
11:20	1471	1.40	10117.20	33
11:30	0543	1.50	10117.30	33
11:40	1475	1.70	10117.50	35
12:10	1553	2.20	10118.00	37
12:30	1734	2.70	10118.50	39
12:40	1745	3.00	10118.80	41
12:50	2053	3.20	10119.00	40
13:00	2021	3.50	10119.30	42
13:10	2050	3.80	10119.60	43
13:20	0542	4.00	10119.80	41
13:30	0336	4.10	10119.90	36 etc

(Time-Power-YieldDay20-TotalYieldInverter-TemperatureInverter)

*/